Mathematical Foundations of Computer Science Constructor University Dr. Jürgen Schönwälder Module: CH-233 Date: 2024-09-06 Due: 2023-09-13

Problem Sheet #1

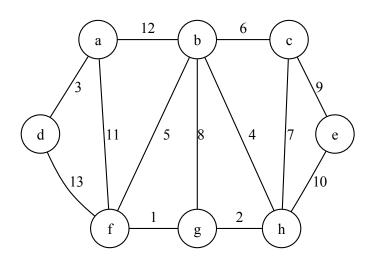
Problem 1.1: *minimum spanning trees*

(2+3 = 5 points)

We have introduced Kruskal's algorithm for constructing random spanning trees. Edges were selected randomly and added to the spanning tree as long as the nodes connected by the edges belong to different equivalence classes.

Kruskal's algorithm solves a slightly more difficult problem: Given a graph G = (V, A) and a cost function $c: A \to \mathbb{R}$ indicating the cost of the edges, calculate the spanning tree T = (V, E) such that $C = \sum_{e \in E} c(e)$ is minimal (also called a minimum spanning tree). Kruskal's algorithm solves this problem by selecting in each step an edge that joins two equivalence classes and has the minimum cost of all edges still available.

Consider the following graph. The labels next to the edges indicate the cost of the different edges.



- a) Define the graph G = (V, A) shown above by defining the set of verticies V and the set of edges A (ignore the costs here).
- b) Construct a minimal spanning tree T = (V, E) using Kruskal's algorithm. For each step, write down the set of equivalence classes C and the edges in E. What is the overall cost S of the resulting spanning tree? You start with:

| $E = \{\}$ $C = \{\ldots\}$ | initialization, $S = 0$ |
|-----------------------------|-------------------------|
| $E = \dots$ $C = \dots$ | step 1, $S = \dots$ |
| $E = \dots$ $C = \dots$ | step 2, $S = \dots$ |

. . .

Problem 1.2: boyer moore algorithm

You have designed a simple robot that can turn left (L), turn right (R), move one step forward (F), and pause (P) for short time. The robot is programmed by a sequence of robot instructions. For example, the sequence FFLFLFRFRFFLFRF will direct the robot through the maze shown on the slides discussing maze generation algorithms. Using the Boyer Moore algorithm, we can determine whether a robot program contains certain movement sequences.

Let $\Sigma = \{L, R, F, P\}$ be an alphabet and $t \in \Sigma^*$ be a text of length n describing a program for the robot. Let $p \in \Sigma^*$ be a pattern of length m. We are looking for the first occurrence of p in t.

Consider the text t = FPLFLFRFRFPLFPLFRF and the pattern p = LFPLF.

- a) Execute the naive string search algorithm. Show all alignments and indicate comparisons performed by writing uppercase characters and comparisons skipped by writing lowercase characters. How many alignments are used? How many comparisons are done?
- b) Execute the Boyer-Moore string search algorithm with the bad character rule only. How many alignments are used? How many comparisons are done?
- c) Calculate the lookup table for the bad character rule that indicates the number of alignments that can be skipped if a comparison does not match.